

**VOLUME-09 Part B and C****CONTENTS****III. Electromagnetic Theory**

6.1	Electromagnetic Waves in Matter	1
6.2	Electromagnetic Waves in Conductors	9
6.3	Electromagnetic Waves	12
6.4	Electromagnetic Waves in Vacuum	17
6.5	Polarization	22
7.1	Fresnel's Law, interference, coherence, and diffraction	
8.1	Dispersion Relations in a Hot Plasma	24
9.1	Wave Guides	33
9.2	TE Waves in a Rectangular Wave Guide	35
9.3	The Coaxial Transmission Line	38
10.1	Radiation from dipoles and retarded potentials	39
10.2	Radiation from Charges	49
10.3	Retarded Potentials	53

### III.6. Electromagnetic Waves in free space, dielectrics and conductors & Reflection and refraction, polarization

#### 6.1. Electromagnetic Waves in Matter

##### 1. Propagation in Linear Media:

Inside matter, but in regions where there is no free charge or free current, Maxwell's equations become

$$\left. \begin{aligned} (i) \nabla \cdot \mathbf{D} &= 0, & (iii) \nabla \times \mathbf{E} &= \frac{\partial \mathbf{B}}{\partial t}, \\ (ii) \nabla \cdot \mathbf{B} &= 0, & (iv) \nabla \times \mathbf{H} &= \frac{\partial \mathbf{D}}{\partial t}, \end{aligned} \right\} \dots 1$$

If the medium is linear,

$$\mathbf{D} = \epsilon \mathbf{E}, \quad \mathbf{H} = \frac{1}{\mu} \mathbf{B} \quad \dots 2$$

And homogeneous (so  $\epsilon$  and  $\mu$  do not vary from point to point), Maxwell's equations reduce to

$$\left. \begin{aligned} (i) \nabla \cdot \mathbf{E} &= 0, & (iii) \nabla \times \mathbf{E} &= \frac{\partial \mathbf{B}}{\partial t}, \\ (ii) \nabla \cdot \mathbf{B} &= 0, & (iv) \nabla \times \mathbf{B} &= \mu \epsilon \frac{\partial \mathbf{E}}{\partial t}, \end{aligned} \right\} \dots 3$$

Evidently electromagnetic waves propagate through a linear homogeneous medium at a speed

$$v = \frac{1}{\sqrt{\epsilon \mu}} = \frac{c}{n}, \quad \dots 4$$

Where,  $n \equiv \sqrt{\frac{\epsilon \mu}{\epsilon_0 \mu_0}}$  = is the **index of refraction** of the material.  $\dots 5$

For most materials,  $\mu$  is very close to  $\mu_0$ , so

$$n \cong \sqrt{\epsilon_r}, \quad \dots 6$$

where,  $\epsilon_r$  is the dielectric constant.

Since  $\epsilon_r$  is almost always greater than 1, light travels more slowly through matter — a fact that is well known from optics.

All of our previous results carry over, with the simple transaction,

$\epsilon_0 \rightarrow \epsilon$ ,  $\mu_0 \rightarrow \mu$  and hence  $c \rightarrow v$ .

The energy density is,

$$u = \frac{1}{2} \left( \epsilon E^2 + \frac{1}{\mu} B^2 \right), \quad \dots 7$$

And the Poynting vector is

$$\mathbf{S} = \frac{1}{\mu} (\mathbf{E} \times \mathbf{B}) \quad \dots 8$$

For monochromatic plane waves the frequency and wave number are related by,

$$\omega = kv,$$

the amplitude of  $\mathbf{B}$  is,

$$\mathbf{B} = 1/v \mathbf{E}$$

and the intensity is,

$$I = \frac{1}{2} \epsilon v E_0^2. \quad \dots 9$$

As in the case of waves on a string, we expect to get a reflected wave and a transmitted wave.

$$\left. \begin{array}{ll} (i) \epsilon_1 E_1^\perp = \epsilon_2 E_2^\perp, & (iii) \mathbf{E}_1^\parallel = \mathbf{E}_2^\parallel \\ (ii) B_1^\perp = B_2^\perp, & (iv) \frac{1}{\mu_1} \mathbf{B}_1^\parallel = \frac{1}{\mu_2} \mathbf{B}_2^\parallel \end{array} \right\} \quad \dots 10$$

These equations relate the electric and magnetic fields just to the left and just to the right of the interface between two linear media.

## 2. Reflection and Transmission at Normal Incidence:

Suppose the  $xy$  plane forms the boundary between two linear media. A plane wave of frequency  $\omega$ , travelling in the  $z$  direction and polarized in the  $x$  direction, approaches the interface from the left.

$$\left. \begin{array}{l} \tilde{\mathbf{E}}_I(z,t) = \tilde{E}_{0I} e^{i(k_1 z - \omega t)} \hat{\mathbf{x}} \\ \tilde{\mathbf{B}}_I(z,t) = \frac{1}{v_1} \tilde{E}_{0I} e^{i(k_1 z - \omega t)} \hat{\mathbf{y}} \end{array} \right\} \quad \dots 11$$

It gives rise to a reflected wave,

$$\left. \begin{array}{l} \tilde{\mathbf{E}}_R(z,t) = \tilde{E}_{0R} e^{i(k_1 z - \omega t)} \hat{\mathbf{x}} \\ \tilde{\mathbf{B}}_R(z,t) = \frac{1}{v_1} \tilde{E}_{0R} e^{i(k_1 z - \omega t)} \hat{\mathbf{y}} \end{array} \right\} \quad \dots 12$$

which travels back to the left in medium (1), and a transmitted wave

$$\left. \begin{aligned} \tilde{\mathbf{E}}_T(z,t) &= \tilde{E}_{0T} e^{i(k_2 z - \omega t)} \hat{\mathbf{x}} \\ \tilde{\mathbf{B}}_T(z,t) &= \frac{1}{v_2} \tilde{E}_{0T} e^{i(k_2 z - \omega t)} \hat{\mathbf{y}} \end{aligned} \right\} \quad \dots 13$$

which continues on the right in medium (2).

At  $z = 0$ , the combined fields on the left,  $\tilde{\mathbf{E}}_I + \tilde{\mathbf{E}}_R$  and  $\tilde{\mathbf{B}}_I + \tilde{\mathbf{B}}_R$ , must join the fields on the right,  $\mathbf{E}_T$  and  $\mathbf{B}_T$ , in accordance with the boundary conditions.

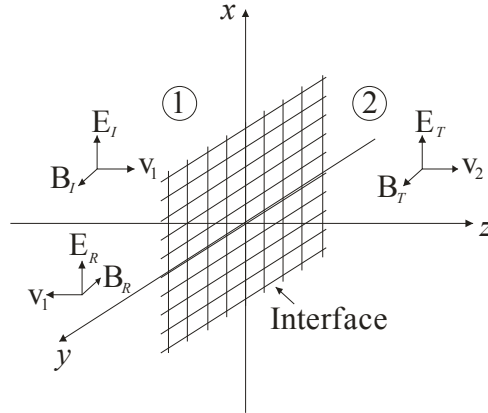


Figure 1

In case there are no components perpendicular to the surface, so (i) and (ii) are trivial. However, (iii) requires that

$$\tilde{E}_{0I} + \tilde{E}_{0R} = \tilde{E}_{0T}, \quad \dots 14$$

while (iv) says

$$\frac{1}{\mu_1} \left( \frac{1}{v_1} \tilde{E}_{0I} - \frac{1}{v_1} \tilde{E}_{0R} \right) = \frac{1}{\mu_2} \left( \frac{1}{v_2} \tilde{E}_{0T} \right), \quad \dots 15$$

or

$$\tilde{E}_{0I} - \tilde{E}_{0R} = \beta \tilde{E}_{0T}, \quad \dots 16$$

where,

$$\beta \equiv \frac{\mu_1 v_1}{\mu_2 v_2} = \frac{\mu_1 n_2}{\mu_2 n_1}. \quad \dots 17$$

Equations (14) and (16) are easily solved for the outgoing amplitudes, in terms of the incident amplitude:

$$\tilde{E}_{0R} = \left( \frac{1-\beta}{1+\beta} \right) \tilde{E}_{0I}, \quad \tilde{E}_{0T} = \left( \frac{2}{1+\beta} \right) \tilde{E}_{0I}. \quad \dots 18$$

These results are strikingly similar to the ones for waves on a string. Indeed, if the permittivities  $\mu$  are close to their values in vacuum (as, remember, they are for most media),

Then

$$\beta = v_1/v_2,$$

and we have

$$\tilde{E}_{0R} = \left( \frac{v_2 - v_1}{v_2 + v_1} \right) \tilde{E}_{0I}, \quad \tilde{E}_{0T} = \left( \frac{2v_2}{v_2 + v_1} \right) \tilde{E}_{0I} \quad \dots 19$$

In that case, as before, the wave is in phase (right side up) if  $v_2 > v_1$  and out of phase (upside down) if  $v_2 < v_1$ ; the real amplitudes are related by,

$$E_{0R} = \left| \frac{v_2 - v_1}{v_2 + v_1} \right| E_{0I}, \quad E_{0T} = \left( \frac{2v_2}{v_2 + v_1} \right) E_{0I} \quad \dots 20$$

Or, in terms of the indices of refraction,

$$E_{0R} = \left| \frac{n_1 - n_2}{n_1 + n_2} \right| E_{0I}, \quad E_{0T} = \left( \frac{2n_2}{n_1 + n_2} \right) E_{0I} \quad \dots 21$$

According to Equation (19), the intensity (average power per unit area) is,

$$I = \frac{1}{2} \epsilon v E_0^2.$$

If (again)  $\mu_1 = \mu_2 = \mu_0$ , then the ratio of the reflected intensity to the incident intensity is,

$$R \equiv \frac{I_R}{I_I} = \left( \frac{E_{0R}}{E_{0I}} \right)^2 = \left( \frac{n_1 - n_2}{n_1 + n_2} \right)^2, \quad \dots 22$$

whereas the ratio of the transmitted intensity to the incident intensity is,

$$T \equiv \frac{I_T}{I_I} = \frac{\epsilon_2 v_2}{\epsilon_1 v_1} \left( \frac{E_{0T}}{E_{0I}} \right)^2 = \frac{4n_1 n_2}{(n_1 + n_2)^2}. \quad \dots 23$$

$R$  is called the **reflection coefficient** and  $T$  the **transmission coefficient**; they measure the fraction of the incident energy that is reflected and transmitted, respectively.

Notice that,

$$R + T = 1, \quad \dots 24$$

as conservation of energy requires. For instance, when light passes from air ( $n_1 = 1$ ) into glass ( $n_2 = 1.5$ ).  $R = 0.04$  and  $T = 0.96$ . Not surprisingly, most of the light is transmitted.

*Continued with...Page 5 Onwards.... It's So Gooooood!!!, Buy it now...!*